

EM algorithm derivations and supplementary data

1 Algorithm derivations

1.1 Derivation of E-step filter updates

1.1.1 Probability mass function of m_k

$$\begin{aligned}
P(m_k|x_k) &= p_k^{m_k} (1-p_k)^{1-m_k} \\
&= \exp \left\{ \log \left[p_k^{m_k} (1-p_k)^{1-m_k} \right] \right\} \\
&= \exp \left[m_k \log(p_k) + (1-m_k) \log(1-p_k) \right] \\
&= \exp \left[m_k \log \left(\frac{p_k}{1-p_k} \right) + \log(1-p_k) \right] \\
&= \exp \left[m_k(\beta_0 + \beta_1 x_k) + \log \left(\frac{1}{1+e^{\beta_0+\beta_1 x_k}} \right) \right]
\end{aligned} \tag{1}$$

1.1.2 Mean and variance of the posterior density function $p(x_k|y^k)$

We follow an approach similar to [1] in deriving the filter updates. Recall that linear models are assumed to relate sympathetic arousal to the phasic-derived and tonic components.

$$r_k = \gamma_0 + \gamma_1 x_k + v_k \tag{2}$$

$$s_k = \delta_0 + \delta_1 x_k + w_k \tag{3}$$

We take the two noise terms v_k and w_k to be independent of each other. Consequently, the density functions $p(r_k|x_k)$ and $p(s_k|x_k)$ conditioned on already having observed x_k are independent of each other in the following derivation.

$$\begin{aligned}
p(x_k|y^k) &= \frac{p(x_k|y^{k-1})p(y_k|x_k)}{p(y_k|y^{k-1})} \\
&= \frac{p(x_k|y^{k-1})P(m_k|x_k)p(r_k|x_k)p(s_k|x_k)P(n_{k,1:J}|x_k)}{p(y_k|y^{k-1})} \\
&\propto \exp \left[\frac{-(x_k - x_{k|k-1})^2}{2\sigma_{k|k-1}^2} + m_k \log \left(\frac{p_k}{1-p_k} \right) + \log(1-p_k) \right. \\
&\quad \left. - \frac{(r_k - \gamma_0 - \gamma_1 x_k)^2}{2\sigma_v^2} - \frac{(s_k - \delta_0 - \delta_1 x_k)^2}{2\sigma_w^2} + \sum_{j=1}^J \log(\lambda_{k,j}\Delta) n_{k,j} - \lambda_{k,j}\Delta \right]
\end{aligned} \tag{4}$$

$$\begin{aligned}
\log \left[p(x_k|y^k) \right] &= \left[\frac{-(x_k - x_{k|k-1})^2}{2\sigma_{k|k-1}^2} + m_k \log \left(\frac{p_k}{1-p_k} \right) + \log(1-p_k) \right. \\
&\quad \left. - \frac{(r_k - \gamma_0 - \gamma_1 x_k)^2}{2\sigma_v^2} - \frac{(s_k - \delta_0 - \delta_1 x_k)^2}{2\sigma_w^2} + \sum_{j=1}^J \log(\lambda_{k,j}\Delta) n_{k,j} - \lambda_{k,j}\Delta \right] + \text{const}
\end{aligned} \tag{5}$$

We take the partial derivative of the logarithm term above and set it to 0 to solve for the mean.

$$\begin{aligned} \frac{\partial}{\partial x_k} \log [p(x_k|y^k)] &= \frac{-(x_k - x_{k|k-1})}{\sigma_{k|k-1}^2} + \beta_1(m_k - p_k) + \frac{\gamma_1(r_k - \gamma_0 - \gamma_1 x_k)}{\sigma_v^2} \\ &+ \frac{\delta_1(s_k - \delta_0 - \delta_1 x_k)}{\sigma_w^2} + \sum_{j=1}^J \frac{1}{\lambda_{k,j|k}} \frac{\partial \lambda_{k,j|k}}{\partial x_k} (n_{k,j} - \lambda_{k,j|k} \Delta) = 0. \end{aligned} \quad (6)$$

Solving for x_k in the equation above provides the filter update for $x_{k|k}$. We have taken,

$$\frac{\partial p_k}{\partial x_k} = \beta_1 p_k (1 - p_k) \quad (7)$$

when calculating the partial derivative. Similarly, the second partial derivative is,

$$\begin{aligned} \frac{\partial^2}{\partial x_k^2} \log [p(x_k|y^k)] &= \frac{-1}{\sigma_{k|k-1}^2} - \beta_1 \frac{\partial p_k}{\partial x_k} - \frac{\gamma_1^2}{\sigma_v^2} - \frac{\delta_1^2}{\sigma_w^2} + \frac{\partial}{\partial x_k} \left[\sum_{j=1}^J \frac{1}{\lambda_{k,j|k}} \frac{\partial \lambda_{k,j|k}}{\partial x_k} (n_{k,j} - \lambda_{k,j|k} \Delta) \right] \\ &= \frac{-1}{\sigma_{k|k-1}^2} - \beta_1^2 p_k (1 - p_k) - \frac{\gamma_1^2}{\sigma_v^2} - \frac{\delta_1^2}{\sigma_w^2} \\ &+ \sum_{j=1}^J \left[\frac{1}{\lambda_{k,j|k}} \frac{\partial^2 \lambda_{k,j|k}}{\partial x_k^2} (n_{k,j} - \lambda_{k,j|k} \Delta) - \frac{n_{k,j}}{\lambda_{k,j|k}^2} \left(\frac{\partial \lambda_{k,j|k}}{\partial x_k} \right)^2 \right]. \end{aligned} \quad (8)$$

The filter update for $\sigma_{k|k}^2$ is given by [1],

$$\sigma_{k|k}^2 = \left\{ -\frac{\partial^2}{\partial x_k^2} \log [p(x_k|y^k)] \right\}^{-1}. \quad (9)$$

1.2 Derivation of the M-step updates

1.2.1 Complete data log-likelihood

Taking $\mathcal{X}^K = \{x_1, x_2, \dots, x_K\}$, the complete data likelihood conditioned on the model parameters Θ is given by,

$$\begin{aligned} p(\mathcal{Y}^K, \mathcal{X}^K | \Theta) &= \prod_{k=1}^K p_k^{m_k} (1 - p_k)^{1-m_k} \times \prod_{k=1}^K \frac{1}{\sqrt{2\pi\sigma_v^2}} e^{-\frac{(r_k - \gamma_0 - \gamma_1 x_k)^2}{2\sigma_v^2}} \\ &\times \prod_{k=1}^K \frac{1}{\sqrt{2\pi\sigma_w^2}} e^{-\frac{(s_k - \delta_0 - \delta_1 x_k)^2}{2\sigma_w^2}} \times \prod_{k=1}^K e^{\sum_{j=1}^J \log(\lambda_{k,j} \Delta) n_{k,j} - \lambda_{k,j} \Delta} \\ &\times \prod_{k=1}^K \frac{1}{\sqrt{2\pi\sigma_\varepsilon^2}} e^{-\frac{(x_k - \rho x_{k-1} - \alpha I_k)^2}{2\sigma_\varepsilon^2}}. \end{aligned} \quad (10)$$

The expected log-likelihood is,

$$Q = \sum_{k=1}^K \mathbb{E} \left[m_k (\beta_0 + \beta_1 x_k) - \log (1 + e^{\beta_0 + \beta_1 x_k}) \right] + \frac{(-K)}{2} \log (2\pi\sigma_v^2)$$

$$\begin{aligned}
& - \sum_{k=1}^K \frac{\mathbb{E}[(r_k - \gamma_0 - \gamma_1 x_k)^2]}{2\sigma_v^2} + \frac{(-K)}{2} \log(2\pi\sigma_w^2) - \sum_{k=1}^K \frac{\mathbb{E}[(s_k - \delta_0 - \delta_1 x_k)^2]}{2\sigma_w^2} \\
& + \sum_{k=1}^K \sum_{j=1}^J \mathbb{E}[\log(\lambda_{k,j}\Delta)n_{k,j} - \lambda_{k,j}\Delta] + \frac{(-K)}{2} \log(2\pi\sigma_\varepsilon^2) - \sum_{k=1}^K \frac{\mathbb{E}[(x_k - \rho x_{k-1} - \alpha I_k)^2]}{2\sigma_\varepsilon^2}.
\end{aligned} \tag{11}$$

Following [2], we take

$$x_{k|K} = \mathbb{E}[x_k | \mathcal{Y}^K, \Theta] \tag{12}$$

$$U_k = \mathbb{E}[x_k^2 | \mathcal{Y}^K, \Theta] \tag{13}$$

$$U_{k,k+1} = \mathbb{E}[x_k x_{k+1} | \mathcal{Y}^K, \Theta]. \tag{14}$$

1.2.2 M-step updates for α and ρ

Let Q_1 denote the term in Q that contains α and ρ .

$$Q_1 = \frac{1}{2\sigma_\varepsilon^2} \sum_{k=1}^K \mathbb{E}[(x_k - \rho x_{k-1} - \alpha I_k)^2] \tag{15}$$

While it is possible to determine the starting state x_0 as a separate parameter, we follow one of the options in [2, 3] and set $x_0 = x_1$. This permits some bias at the beginning. Therefore,

$$Q_1 = \frac{1}{2\sigma_\varepsilon^2} \left\{ \sum_{k=2}^K \mathbb{E}[(x_k - \rho x_{k-1} - \alpha I_k)^2] + \mathbb{E}[(\alpha I_1)^2] \right\}. \tag{16}$$

We take the partial derivatives of Q_1 with respect to α and ρ and set them to 0 to obtain the M-step updates.

$$\begin{aligned}
\frac{\partial Q_1}{\partial \alpha} &= \sum_{k=2}^K \mathbb{E}[-2I_k(x_k - \rho x_{k-1} - \alpha I_k)] + 2\alpha I_1^2 \\
0 &= -\sum_{k=2}^K I_k \mathbb{E}[x_k] + \rho \sum_{k=2}^K I_k \mathbb{E}[x_{k-1}] + \alpha \sum_{k=1}^K I_k^2 \\
&= -\sum_{k=2}^K I_k x_{k|K} + \rho \sum_{k=2}^K I_k x_{k-1|K} + \alpha \sum_{k=1}^K I_k^2
\end{aligned} \tag{17}$$

$$\begin{aligned}
\frac{\partial Q_1}{\partial \rho} &= \sum_{k=2}^K \mathbb{E}[-2x_{k-1}(x_k - \rho x_{k-1} - \alpha I_k)] \\
0 &= -\sum_{k=2}^K \mathbb{E}[x_k x_{k-1}] + \rho \sum_{k=2}^K \mathbb{E}[x_{k-1}^2] + \alpha \sum_{k=2}^K I_k \mathbb{E}[x_{k-1}] \\
&= -\sum_{k=1}^{K-1} U_{k,k+1} + \rho \sum_{k=1}^{K-1} U_k + \alpha \sum_{k=2}^K I_k x_{k-1|K}
\end{aligned} \tag{18}$$

(19)

The solutions to these simultaneous equations provide α and ρ .

1.2.3 M-step updates for γ_0 , γ_1 , δ_0 and δ_1

Let Q_2 denote the term in Q containing γ_0 and γ_1 .

$$Q_2 = \sum_{k=1}^K \frac{\mathbb{E}[(r_k - \gamma_0 - \gamma_1 x_k)^2]}{2\sigma_v^2} \quad (20)$$

Taking the partial derivatives with respect to γ_0 and γ_1 yields,

$$\begin{aligned} \frac{\partial Q_2}{\partial \gamma_0} &= \sum_{k=1}^K -2\mathbb{E}[r_k - \gamma_0 - \gamma_1 x_k] \\ 0 &= -\sum_{k=1}^K r_k + \gamma_0 K + \gamma_1 \sum_{k=1}^K \mathbb{E}[x_k] \\ &= -\sum_{k=1}^K r_k + \gamma_0 K + \gamma_1 \sum_{k=1}^K x_{k|K} \end{aligned} \quad (21)$$

$$\begin{aligned} \frac{\partial Q_2}{\partial \gamma_1} &= \sum_{k=1}^K -2\mathbb{E}[x_k(r_k - \gamma_0 - \gamma_1 x_k)] \\ 0 &= -\sum_{k=1}^K r_k \mathbb{E}[x_k] + \gamma_0 \sum_{k=1}^K \mathbb{E}[x_k] + \gamma_1 \sum_{k=1}^K \mathbb{E}[x_k^2] \\ &= -\sum_{k=1}^K r_k x_{k|K} + \gamma_0 \sum_{k=1}^K x_{k|K} + \gamma_1 \sum_{k=1}^K U_k. \end{aligned} \quad (22)$$

The solutions to these simultaneous equations provide γ_0 and γ_1 . δ_0 and δ_1 may be obtained similarly from the term in Q containing s_k .

1.2.4 M-step updates for σ_v^2 and σ_w^2

Let Q_3 denote the term in Q containing σ_v^2 .

$$Q_3 = \frac{-K}{2} \log(2\pi\sigma_v^2) - \sum_{k=1}^K \frac{\mathbb{E}[(r_k - \gamma_0 - \gamma_1 x_k)^2]}{2\sigma_v^2} \quad (23)$$

We take the partial derivative with respect to σ_v^2 and set it to 0.

$$\frac{\partial Q_3}{\partial \sigma_v^2} = \frac{-K}{2\sigma_v^2} + \frac{1}{2\sigma_v^4} \sum_{k=1}^K \mathbb{E}[(r_k - \gamma_0 - \gamma_1 x_k)^2] = 0 \quad (24)$$

$$\begin{aligned} \sigma_v^2 &= \frac{1}{K} \sum_{k=1}^K \mathbb{E}[(r_k - \gamma_0 - \gamma_1 x_k)^2] \\ &= \frac{1}{K} \left\{ \sum_{k=1}^K r_k^2 + K\gamma_0^2 + \gamma_1^2 \sum_{k=1}^K \mathbb{E}[x_k^2] - 2\gamma_0 \sum_{k=1}^K r_k - 2\gamma_1 \sum_{k=1}^K r_k \mathbb{E}[x_k] + 2\gamma_0\gamma_1 \sum_{k=1}^K \mathbb{E}[x_k] \right\} \\ &= \frac{1}{K} \left\{ \sum_{k=1}^K r_k^2 + K\gamma_0^2 + \gamma_1^2 \sum_{k=1}^K U_k - 2\gamma_0 \sum_{k=1}^K r_k - 2\gamma_1 \sum_{k=1}^K r_k x_{k|K} + 2\gamma_0\gamma_1 \sum_{k=1}^K x_{k|K} \right\}. \end{aligned} \quad (25)$$

The update for σ_w^2 may be obtained likewise.

1.2.5 M-step update for σ_ε^2

Let Q_4 denote the term in Q containing σ_ε^2 .

$$\begin{aligned} Q_4 &= \frac{-K}{2} \log(2\pi\sigma_\varepsilon^2) - \sum_{k=1}^K \frac{\mathbb{E}[(x_k - \rho x_{k-1} - \alpha I_k)^2]}{2\sigma_\varepsilon^2} \\ &= \frac{-K}{2} \log(2\pi\sigma_\varepsilon^2) - \sum_{k=2}^K \frac{\mathbb{E}[(x_k - \rho x_{k-1} - \alpha I_k)^2]}{2\sigma_\varepsilon^2} - \frac{\mathbb{E}[(\alpha I_1)^2]}{2\sigma_\varepsilon^2} \end{aligned} \quad (26)$$

We take the partial derivative with respect to σ_ε^2 and set it to 0.

$$\frac{\partial Q_4}{\partial \sigma_\varepsilon^2} = \frac{-K}{2\sigma_\varepsilon^2} + \frac{1}{2\sigma_\varepsilon^4} \sum_{k=2}^K \mathbb{E}[(x_k - \rho x_{k-1} - \alpha I_k)^2] + \frac{(\alpha I)^2}{2\sigma_\varepsilon^4} = 0 \quad (27)$$

$$\begin{aligned} \sigma_\varepsilon^2 &= \frac{1}{K} \sum_{k=2}^K \left\{ \mathbb{E}[x_k^2] - 2\rho\mathbb{E}[x_k x_{k-1}] + \rho^2\mathbb{E}[x_{k-1}^2] - 2\alpha I_k \mathbb{E}[x_k] + 2\alpha\rho I_k \mathbb{E}[x_{k-1}] \right\} + \frac{\alpha^2}{K} \sum_{k=1}^K I_k^2 \\ &= \frac{1}{K} \left\{ \sum_{k=2}^K U_k - 2\rho \sum_{k=1}^{K-1} U_{k,k+1} + \rho^2 \sum_{k=1}^{K-1} U_k - 2\alpha \sum_{k=2}^K I_k x_{k|K} + 2\alpha\rho \sum_{k=2}^K I_k x_{k-1|K} + \alpha^2 \sum_{k=1}^K I_k^2 \right\} \end{aligned} \quad (28)$$

1.2.6 M-step updates for β_0 and β_1

Let Q_5 denote the expectation term containing β_0 and β_1 .

$$Q_5 = \sum_{k=1}^K \mathbb{E}\left[m_k(\beta_0 + \beta_1 x_k) - \log(1 + e^{\beta_0 + \beta_1 x_k})\right] \quad (29)$$

We perform a Taylor expansion of the logarithm term around $x_{k|K}[1]$.

$$\log(1 + e^{\beta_0 + \beta_1 x_k}) \approx \log(1 + e^{\beta_0 + \beta_1 x_{k|K}}) + \beta_1 p_{k|K}(x_k - x_{k|K}) + \frac{\beta_1^2}{2} p_{k|K}(1 - p_{k|K})(x_k - x_{k|K})^2 \quad (30)$$

Taking the expected value on both sides,

$$\begin{aligned} \mathbb{E}\left[\log(1 + e^{\beta_0 + \beta_1 x_k})\right] &\approx \log(1 + e^{\beta_0 + \beta_1 x_{k|K}}) + \beta_1 p_{k|K} \mathbb{E}[x_k - x_{k|K}] + \frac{\beta_1^2}{2} p_{k|K} (1 - p_{k|K}) \mathbb{E}[(x_k - x_{k|K})^2] \\ &= \log(1 + e^{\beta_0 + \beta_1 x_{k|K}}) + 0 + \frac{\beta_1^2}{2} p_{k|K} (1 - p_{k|K}) \sigma_{k|K}^2. \end{aligned} \quad (31)$$

Therefore,

$$Q_5 \approx \sum_{k=1}^K \left[m_k(\beta_0 + \beta_1 x_{k|K}) - \log(1 + e^{\beta_0 + \beta_1 x_{k|K}}) - \frac{\beta_1^2}{2} p_{k|K} (1 - p_{k|K}) \sigma_{k|K}^2 \right]. \quad (32)$$

Now,

$$\frac{\partial p_{k|K}}{\partial \beta_0} = \frac{\partial}{\partial \beta_0} \left[\frac{1}{1 + e^{-(\beta_0 + \beta_1 x_{k|K})}} \right]$$

$$\begin{aligned}
&= \frac{(-1)}{\left[1 + e^{-(\beta_0 + \beta_1 x_{k|K})}\right]^2} \times \left[-e^{-(\beta_0 + \beta_1 x_{k|K})} \right] \\
&= p_{k|K}(1 - p_{k|K}). \tag{33}
\end{aligned}$$

And similarly,

$$\frac{\partial p_{k|K}}{\partial \beta_1} = p_{k|K}(1 - p_{k|K})x_{k|K}. \tag{34}$$

Taking the partial derivative w.r.t. β_0 ,

$$\begin{aligned}
\frac{\partial Q_5}{\partial \beta_0} &= \sum_{k=1}^K \left\{ m_k - p_{k|K} - \frac{\beta_1^2 \sigma_{k|K}^2}{2} \frac{\partial}{\partial \beta_0} [p_{k|K}(1 - p_{k|K})] \right\} \\
0 &= \sum_{k=1}^K \left[m_k - p_{k|K} - \frac{\beta_1^2 \sigma_{k|K}^2}{2} (1 - p_{k|K})(1 - 2p_{k|K})p_{k|K} \right]. \tag{35}
\end{aligned}$$

And similarly for β_1 we arrive at,

$$\begin{aligned}
\frac{\partial Q_5}{\partial \beta_1} &= \sum_{k=1}^K \left[m_k x_{k|K} - x_{k|K} p_{k|K} \right. \\
&\quad \left. - \frac{\beta_1 \sigma_{k|K}^2}{2} p_{k|K} (1 - p_{k|K}) [2 + \beta_1 x_{k|K} (1 - 2p_{k|K})] \right] \\
&= 0 \tag{36}
\end{aligned}$$

1.2.7 Approximation for the expectation term containing $\lambda_{k,j}$

Let Q_6 denote the expectation term containing $\lambda_{k,j}$.

$$Q_6 = \sum_{k=1}^K \sum_{j=1}^J \mathbb{E} \left[\log(\lambda_{k,j} \Delta) n_{k,j} - \lambda_{k,j} \Delta \right] \tag{37}$$

We perform a Taylor expansion of the summed term around $x_{k|K}$ [1].

$$\begin{aligned}
\log(\lambda_{k,j} \Delta) n_{k,j} - \lambda_{k,j} \Delta &\approx \log(\lambda_{k,j|K} \Delta) n_{k,j} - \lambda_{k,j|K} \Delta + \frac{1}{\lambda_{k,j|K}} \frac{\partial \lambda_{k,j|K}}{\partial x_k} (n_{k,j} - \lambda_{k,j|K} \Delta)(x_k - x_{k|K}) \\
&\quad + \frac{1}{2} \left[\frac{1}{\lambda_{k,j|K}} \frac{\partial^2 \lambda_{k,j|K}}{\partial x_k^2} (n_{k,j} - \lambda_{k,j|K} \Delta) - \frac{n_{k,j}}{\lambda_{k,j|K}^2} \left(\frac{\partial \lambda_{k,j|K}}{\partial x_k} \right)^2 \right] (x_k - x_{k|K})^2 \tag{38}
\end{aligned}$$

Taking the expected value on both sides,

$$\begin{aligned}
\mathbb{E} [\log(\lambda_{k,j} \Delta) n_{k,j} - \lambda_{k,j|K} \Delta] &\approx \log(\lambda_{k,j|K} \Delta) n_{k,j} - \lambda_{k,j|K} \Delta + \frac{1}{\lambda_{k,j|K}} \frac{\partial \lambda_{k,j|K}}{\partial x_k} (n_{k,j} - \lambda_{k,j|K} \Delta) \mathbb{E}[x_k - x_{k|K}] \\
&\quad + \frac{1}{2} \left[\frac{1}{\lambda_{k,j|K}} \frac{\partial^2 \lambda_{k,j|K}}{\partial x_k^2} (n_{k,j} - \lambda_{k,j|K} \Delta) - \frac{n_{k,j}}{\lambda_{k,j|K}^2} \left(\frac{\partial \lambda_{k,j|K}}{\partial x_k} \right)^2 \right] \mathbb{E}[x_k - x_{k|K}]^2 \\
&\approx \log(\lambda_{k,j|K} \Delta) n_{k,j} - \lambda_{k,j|K} \Delta + 0
\end{aligned}$$

$$+ \frac{1}{2} \left[\frac{1}{\lambda_{k,j|K}} \frac{\partial^2 \lambda_{k,j|K}}{\partial x_k^2} (n_{k,j} - \lambda_{k,j|K} \Delta) - \frac{n_{k,j}}{\lambda_{k,j|K}^2} \left(\frac{\partial \lambda_{k,j|K}}{\partial x_k} \right)^2 \right] \sigma_{k|K}^2. \quad (39)$$

Therefore,

$$Q_6 \approx \sum_{k=1}^K \sum_{j=1}^J \log(\lambda_{k,j|K} \Delta) n_{k,j} - \lambda_{k,j|K} \Delta + \frac{1}{2} \left[\frac{1}{\lambda_{k,j|K}} \frac{\partial^2 \lambda_{k,j|K}}{\partial x_k^2} (n_{k,j} - \lambda_{k,j|K} \Delta) - \frac{n_{k,j}}{\lambda_{k,j|K}^2} \left(\frac{\partial \lambda_{k,j|K}}{\partial x_k} \right)^2 \right] \sigma_{k|K}^2. \quad (40)$$

2 Experimental data – model parameter estimates

The experimental model parameters estimated for each participant are shown in Table 1. Recall that we estimate x_k at the E-step and calculate the model parameters at the M-step. Recall also that due to computational complexity we split the estimation of the model parameters related to heart rate (i.e., the θ_i 's and the η coefficient) into two parts and calculate them separately. We calculate the θ_i 's offline based on maximum likelihood estimation (MLE) and select η based on which value maximized a log-likelihood term. As pointed out in the “Discussion” section of the main text, this separated-out calculation is a limitation of our model (e.g. it can result in numerical issues). The separate estimation of the heart rate parameters may be the reason why η values are small in the final estimates and why larger η values cause convergence issues in the Newton-Raphson solution for the state update $x_{k|k}$ since the MLE estimation of the θ_i 's may account for much of the heart rate variability. The value of β_1 also turned out to be negative for two participants (the M-step updates turned out to be negative even after the first iteration). Our algorithm provides two options for calculating β_0 and β_1 and it is possible to select the alternate option which sets $\beta_0 = 1$ and calculates β_1 empirically as well if this is to be avoided beforehand. As noted in the main text, a model with a less complex form of the conditional intensity function may enable all the parameters to be recovered at once at the M-step. Lower computational load is also likely to have the benefit of easier deployment onto a wearable platform.

Table 1: Estimated model parameters on experimental data

Participant	α	ρ	δ_0	δ_1	σ_w^2	γ_0	γ_1	σ_v^2	β_0	β_1	σ_ε^2	η
1	0.1339	0.9964	6.0453	0.8501	0.4475	-2.1516	0.8182	0.4881	-4.5533	0.1642	0.0147	-10 ⁻⁴
2	0.1752	0.9984	10.4601	0.8507	0.4731	-6.3457	0.8019	0.5319	-4.9209	0.1145	0.0149	-10 ⁻⁶
3	0.2050	0.9944	15.4847	0.9157	0.5967	-2.9270	0.8805	0.6270	-3.9055	0.2620	0.0196	-10 ⁻⁶
4	0.2122	0.9889	14.8302	0.9337	0.5191	-3.3621	0.9018	0.5515	-3.1620	0.0282	0.0195	-10 ⁻⁶
5	0.1779	0.9963	13.4671	0.8726	0.4388	-3.6769	0.7916	0.5381	-3.7924	-0.1577	0.0150	-10 ⁻⁶
6	0.1532	0.9888	14.6993	0.8869	0.4876	-0.5512	0.8542	0.5247	-3.8582	0.1047	0.0170	-10 ⁻⁵
7	0.0934	0.9986	4.0806	0.8944	0.2311	-2.6035	0.8653	0.2804	-4.1830	0.5256	0.0109	-10 ⁻³
8	0.1231	0.9933	13.5384	0.8755	0.4095	-0.9875	0.8193	0.4829	-3.6242	0.3115	0.0148	-10 ⁻⁴
9	0.1587	0.9966	6.0052	0.9050	0.3256	-4.0313	0.8408	0.4178	-3.6640	-0.1002	0.0141	-10 ⁻⁶
10	0.1365	0.9911	5.6286	0.8804	0.3722	-2.1238	0.8515	0.4127	-4.3647	0.1101	0.0142	-10 ⁻⁴
11	0.1533	0.9947	17.6648	0.9119	0.4269	-0.7794	0.8601	0.4901	-3.4974	0.1716	0.0171	-10 ⁻³
12	0.1536	0.9931	11.5030	0.9069	0.3077	-1.6278	0.8558	0.3835	-4.0583	0.2806	0.0140	-10 ⁻⁶
Participant	θ_i 's											
1	0.0744, 1.1497, -0.1054, -0.1686, 1289.5											
2	0.0733, 1.0793, -0.2674, -0.0028, 0.4085, -0.4041, -0.0461, 0.1289, 0.0149, 1404.5											
3	0.2484, 0.7572, 231.5820											
4	0.2079, 1.3273, -0.4968, -0.0615, -0.0765, -0.0068, 0.0194, 341.5199											
5	0.1319, 1.3161, -0.4226, -0.1202, 0.0481, -0.0603, 0.0376, 561.4294											
6	0.0677, 0.9083, 625.1079											
7	0.1478, 1.0039, -0.2359, 0.0760, 585.6449											
8	0.1289, 1.1844, -0.3928, 699.4618											
9	0.0229, 0.7706, -0.0228, -0.1910, 0.2809, 0.1220, 1253.4											
10	0.1575, 1.1033, -0.3104, 714.4876											
11	0.0990, 1.0544, -0.4583, 0.0098, 0.1616, 0.0254, -0.0710, 0.0540, 0.1015, 107.0561											
12	0.0818, 0.7980, -0.2500, 0.0853, 0.2650, 693.1574											

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