S1 Appendix. Technical details of the MHA algorithm. In this appendix, we give further details of the block-coordinate descent algorithm which we implement to update the model parameters. In practice, we solve the constrained optimisation (8) via the use of projections onto the non-negative quadrant (non-negativity) and Lagrange multipliers. More specifically, we use the objective function:

$$
\tilde{\mathcal{L}} = \mathcal{L} + \frac{\delta}{2} ||W^T W - I_k||_2^2 + \text{tr}(\Gamma^T (W^T W - I_k)),\tag{16}
$$

where  $\Gamma \in \mathbb{R}^{k \times k}$  and  $\delta$  are Lagrange multipliers enforcing the orthonormality constraints.

We employ gradient descent approach to update the estimate of  $W$ . To this end, we follow Monti and Hyvärinen [29] and i ntroduce a gradient step size  $\eta$  and project onto the non-negative orthant at each i teration ( this ensures that the positivity constraint is maintained). The update takes the form

$$
W \leftarrow \mathcal{P}^+ \left( W - \eta \left( \frac{\partial \mathcal{L}}{\partial W} + \delta (WW^\top W - W) + W\Gamma) \right) \right), \tag{17}
$$

where  $\mathcal{P}^+ = \max(0, x)$  denotes the projection onto the non-negative orthant and  $\eta$  is a stepsize parameter. The update for the Lagrange multipliers  $\Gamma$  is given by:

$$
\Gamma \leftarrow \Gamma + \delta(W^{\top} W - I).
$$

In the case of the loading matrix, the gradient update is defined as:

$$
\frac{\partial \mathcal{L}}{\partial W} = \sum_{i=1}^{N} \frac{\partial \mathcal{L}}{\partial \Sigma^{(i)}} \frac{\partial \Sigma^{(i)}}{\partial W}
$$
\n
$$
= \sum_{i=1}^{N} \left( -\Sigma^{(i)} \right)^{-1} + \Sigma^{(i)} \left( -\Sigma^{(i)} \right)^{-1} \left( W G^{(i)} \right), \tag{18}
$$

where we note that via the Sherman-Woodbury identity and using the form of the covariance (3), we can write  $\Sigma^{(i)}$ <sup>-1</sup> as follows:

$$
\Sigma^{(i)^{-1}} = (v^{(i)}I)^{-1} - (v^{(i)}I)^{-1}W(G^{(i)^{-1}} + W^{\top}v^{(i)}IW)^{-1}W^{\top}(v^{(i)}I)^{-1}.
$$
 (19)

For the diagonal matrix of eigenvalues,  $G^{(i)}$ , we can update each matrix independently as follows:

$$
\frac{\partial \mathcal{L}}{\partial G^{(i)}} = \frac{\partial \mathcal{L}}{\partial \Sigma^{(i)}} \frac{\partial \Sigma^{(i)}}{\partial G^{(i)}}
$$
\n
$$
= \sum_{i=1}^{N} \left( -\Sigma^{(i)} \right)^{-1} + \Sigma^{(i)} \left( -\Sigma^{(i)} \right)^{-1} K^{(i)} \Sigma^{(i)} \end{math} (20)
$$