A. A. Cherevko, T. S. Gologush, I. A. Petrenko, V. V. Ostapenko, V. A. Panarin, Modeling of the arteriovenous malformation embolization optimal scenario, Royal Society Open Science

## CABARET scheme

Cauchy problem for Buckley-Leverett equation Let's set this scheme on a uniform rectangular grid

$$x_j = jh, \quad t_n = n\tau, \quad n \ge 0, \tag{1}$$

with constant steps h in space and  $\tau$  in time. The time step is chosen from the stability condition

$$\tau = rh/B, \quad B = \max_{S \in [0,1]} f'(S),$$
 (2)

where  $r \in (0,1)$  is the Courant number. The CABARET scheme uses the flux variables  $u_j^n = S(x_j, t_n)$  and conservative variables  $U_{j+1/2}^n = S(x_{j+1/2}, t_n)$  defined respectively in integer  $x_j$  and half-integer  $x_{j+1/2} = x_j + h/2$  spatial nodes of the difference grid.

First, consider the CABARET scheme application for numerical solution of the Cauchy problem for Buckley-Leverett equation with initial data

$$S(x,0) = S_0(x),$$
 (3)

where  $S_0(x)$  is the given piecewise continuous function. Let  $u_j^n$ ,  $U_{j+1/2}^n$  be the known numerical solution of Cauchy problem on the time layer  $t_n$ , with the following grid approximation of the initial function (3) for n = 0:

$$U_{j+1/2}^{0} = S_0(x_{j+1/2}), \quad u_j^{0} = \frac{U_{j-1/2}^{0} + U_{j+1/2}^{0}}{2}.$$
 (4)

Numerical solution  $u_j^{n+1}$ ,  $U_{j+1/2}^{n+1}$  on the next time layer  $t_{n+1}$  will be found using the CABARET scheme in four stages.

In the first stage, by difference equations

$$\frac{U_{j+1/2}^{n+1/2} - U_{j+1/2}^n}{\tau/2} + \frac{f_{j+1}^n - f_j^n}{h} = 0, \quad f_k^n = f(u_k^n), \tag{5}$$

the conservative variables  $U_{j+1/2}^{n+1/2} = U(x_{j+1/2}, t_{n+1/2})$  are calculated on a halfinteger time layer  $t_{n+1/2} = t_n + \tau/2$ . At the second stage, the numerical fluxes  $f_j^{n+1/2} = f(u_j^{n+1/2})$  are found on the time layer  $t_{n+1/2}$ . At the third stage, by difference equations

$$\frac{U_{j+1/2}^{n+1} - U_{j+1/2}^n}{\tau} + \frac{f_{j+1}^{n+1/2} - f_j^{n+1/2}}{h} = 0$$
(6)

the conservative variables  $U_{j+1/2}^{n+1}$  are calculated on time layer  $t_{n+1}$ . At the fourth stage, the flux variables  $u_j^{n+1}$  are found on the time layer  $t_{n+1}$ . A description of the numerical algorithm in the second and fourth stages is given below.

Flux calculation and correction At the second stage, given that  $f'(S) \ge 0$ , preliminary flux values on the time layer  $t_{n+1/2}$  are calculated in the following way

$$\bar{f}_{j}^{n+1/2} = f\left(\bar{u}_{j}^{n+1/2}\right), \ \bar{u}_{j}^{n+1/2} = \left(u_{j}^{n} + \bar{u}_{j}^{n+1}\right)/2, \ \bar{u}_{j}^{n+1} = 2U_{j-1/2}^{n+1/2} - u_{j-1}^{n}.$$
(7)

With standard double limiter

$$F(u,m,M) = \begin{cases} u, & m \le u \le M, \\ m, & u < m, \\ M, & u > M \end{cases}$$
(8)

these fluxes are corrected by the formula

$$\widetilde{f}_j^{n+1/2} = F\left(\overline{f}_j^{n+1/2}, m_j^n, M_j^n\right),\tag{9}$$

where  $m_j^n = \min\left(f_{j-1/2}^n, f_j^n\right)$ ,  $M_j^n = \max\left(f_{j-1/2}^n, f_j^n\right)$ ,  $f_{j-1/2}^n = f(U_{j-1/2}^n)$ . The correction (9) connected with the difference analogue of the maximum principle, which is satisfied by the exact solutions of the considered problem. However, such a correction does not provide [1] the performance for the difference scheme Harten TVD property [2] and therefore the monotonicity property in the Godunov sense [3].

Therefore, if on the *n*-th time layer in the neighborhood of the grid node  $x_{k+1/2}$  the difference solution is locally monotonic, then an additional correction of the numerical fluxes is performed:

$$U_{k-3/2}^{n} \le u_{k-1}^{n} \le U_{k-1/2}^{n} \le u_{k}^{n} \quad \Rightarrow \quad f_{k}^{n+1/2} = F_{1}\left(\tilde{f}_{k}^{n+1/2}, \varphi_{k-1}^{n}\right), \quad (10)$$

$$U_{k-3/2}^{n} \ge u_{k-1}^{n} \ge U_{k-1/2}^{n} \ge u_{k}^{n} \quad \Rightarrow \quad f_{k}^{n+1/2} = F_{2}\left(\tilde{f}_{k}^{n+1/2}, \varphi_{k-1}^{n}\right), \quad (11)$$

where

$$F_{1}(u, M) = \begin{cases} u, & u \leq M, \\ M, & u \geq M, \end{cases} \quad F_{2}(u, m) = \begin{cases} u, & u \geq m, \\ m, & u \leq m, \\ \varphi_{k-1}^{n} = \frac{\tau}{h} \left( U_{k-1/2}^{n} - u_{k-1}^{n} \right) + f_{k-1}^{n}. \end{cases}$$
(12)

This additional correction maintains the monotonicity of the difference solution  $\left\{u_{j}^{n}, U_{j+1/2}^{n}\right\}$  with respect to the sequence of conservative variables  $\left\{U_{j+1/2}^{n+1}\right\}$  on the time layer  $t_{n+1}$ . The proof of this result, formulated in [4], is carried out on the basis of a method outlined in [5] for the case of approximation by the CABARET scheme of a scalar conservation law with a convex flux. Note that the correction (10)–(12) does not reduce the accuracy of the scheme on local extremes located in the smooth parts of the calculated weak solution.

At the beginning of the fourth stage by the formulas

$$\widetilde{u}_j^{n+1} = 2u_j^{n+1/2} - u_j^n, \quad u_j^{n+1/2} = f^{-1}(f_j^{n+1/2}),$$
(13)

where  $f^{-1}$  is a function inverse to function f, the second preliminary values of the flux variables are determined on the time layer  $t_{n+1}$ . As shown in [6], the preservation in the CABARET scheme of monotonicity with respect to the sequence of conservative variables  $\left\{U_{j+1/2}^{n+1}\right\}$  in the general case does not guarantee the monotonicity of the difference solution with respect to sequences  $\left\{\widetilde{u}_{j}^{n+1}, U_{j+1/2}^{n+1}\right\}$  alternating values of flux  $\widetilde{u}_{j}^{n+1}$  and conservative  $U_{j+1/2}^{n+1}$  variables. Therefore, in conclusion, it is necessary to carry out an additional correction of flux variables

$$u_j^{n+1} = F\left(\tilde{u}_j^{n+1}, m_j^{n+1}, M_j^{n+1}\right),$$
(14)

where  $m_j^{n+1} = \min\left(U_{j-1/2}^{n+1}, U_{j+1/2}^{n+1}\right)$  and  $M_j^{n+1} = \max\left(U_{j-1/2}^{n+1}, U_{j+1/2}^{n+1}\right)$ , ensuring the monotony of the entire difference solution  $\{u_j^{n+1}, U_{j+1/2}^{n+1}\}$  on the time layer  $t_{n+1}$ . Note that the last flux correction (14), which is carried out after applying the main divergent formula (6), does not violate of the CABARET scheme conservativity, since this correction can be considered as the first step in the flux calculating on the time layer  $t_{n+2}$ .

**Initial-boundary value problem** A significant advantage of the CABARET scheme compared to WENO type schemes is that this scheme is defined on a compact three-point spatial stencil located inside a single cell of the difference grid, and therefore, when calculating initial boundary-value problems, it is not necessary for the CABARET scheme to apply auxiliary asymmetric difference equations in the near-boundary grid nodes. To solve the Buckley-Leverett equation with the following initial and boundary conditions:

$$S(0,x) = S_0(x) \equiv 1, \quad x \in [0,L],$$
(15)

$$S(t,0) = g(t) \in [0,1], \quad t \in (0,T], \tag{16}$$

we divide the AVM segment [0, L] into N equal parts of length h = L/N and use the exact grid approximation

$$u_0^n = g(t_n) = g(n\tau) \tag{17}$$

of the boundary condition (16). The basic difference equations (5) and (6) approximating the conservation law  $S_t + f(S)_x = 0$  are applied in all halfinteger nodes  $x_{j+1/2}$  of the difference grid with  $j = \overline{0, N-1}$ . The calculation of fluxes (7) and their correction (9)–(11), as well as the calculation of the flux functions (13), are carried out at all positive integer nodes  $x_j$  with  $j = \overline{1, N}$ . The correction (14) of flux functions is performed in all internal integer nodes  $x_j$  with  $j = \overline{1, N-1}$ .

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