

S1 Appendix

Simulation Details

Network systems described in this manuscript involve two data types, \mathcal{G} and \mathcal{X} with a continuous outcome \mathbf{Y} . For our simulations, it is assumed that there are latent variables that describe sub-matrices contained in \mathcal{G} and \mathcal{X} . It is assumed that there are latent variables that describe the sub-matrix of network features \mathbf{G} contained in \mathcal{G} that lead to the behavior of network features \mathbf{X} contained in \mathcal{X} , which ultimately explain \mathbf{Y} . There is also an interactive effect between \mathbf{G} and \mathbf{X} . In addition to the network features, there may be other features that comprise \mathcal{G} and \mathcal{X} . There are latent variables that describe sub-matrices \mathbf{S} and \mathbf{H} within \mathcal{G} and \mathcal{X} that are individually related to \mathbf{Y} but not each other. These relationships may be expressed as a system of linear equations shown in (1). The covariance matrix Σ' for the latent variables (\mathbf{Y} , \mathbf{X} , \mathbf{G} , \mathbf{S} , \mathbf{H})^T is defined in (2).

$$\begin{aligned}
 \mathbf{Y} &= \beta_{Y|X.G}\mathbf{X} + \beta_{Y|G.X}\mathbf{G} + \beta_{Y|S}\mathbf{S} + \beta_{Y|H}\mathbf{H} + \epsilon_{Y|X,G,S,H} \\
 \mathbf{X} &= \beta_{X|G}\mathbf{G} + \epsilon_{X|G} \\
 \mathbf{G} &= \epsilon_G
 \end{aligned} \tag{1}$$

$$\Sigma' = \begin{bmatrix}
 \sigma_{Y|X.G.S.H} + \sigma_{X|G}\beta_{Y|X.G}^2 + \sigma_G\tau^2 + \sigma_S\beta_{Y|S}^2 + \sigma_H\beta_{Y|H}^2 & \sigma_{X|G}\beta_{Y|X.G} + \tau\sigma_G\beta_{X|G} & \sigma_G\tau & \beta_{Y|S}\sigma_S & \beta_{Y|H}\sigma_H \\
 \sigma_{X|G}\beta_{Y|X.G} + \tau\sigma_G\beta_{X|G} & \beta_{X|G}^2\sigma_G + \sigma_{X|G} & \sigma_G\beta_{X|G} & 0 & 0 \\
 \sigma_G\tau & \sigma_G\beta_{X|G} & \sigma_G & 0 & 0 \\
 \beta_{Y|S}\sigma_S & 0 & 0 & \sigma_S & 0 \\
 \beta_{Y|H}\sigma_H & 0 & 0 & 0 & \sigma_H
 \end{bmatrix} \tag{2}$$

There are also latent variables that describe sub-matrices \mathbf{G}' and \mathbf{X}' within \mathcal{G} and \mathcal{X} that are related

to each other but not related to \mathbf{Y} . Additionally, there are also sub-matrices \mathbf{e}_G and \mathbf{e}_X within \mathcal{G} and \mathcal{X} that contain independent noise variables. The covariance matrix Σ defined in (3) describes the relationships between all latent variables $(\mathbf{Y}, \mathbf{X}, \mathbf{G}, \mathbf{S}, \mathbf{H}, \mathbf{X}', \mathbf{G}', \mathbf{e}_X, \mathbf{e}_G)^T$.

$$\Sigma = \begin{bmatrix} \Sigma' & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \beta_{X|G}^2 \sigma_G + \sigma_{X|G} & \sigma_G \beta_{X|G} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \sigma_G \beta_{X|G} & \sigma_G & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \sigma_{e_X} & 0 \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & 0 & \sigma_{e_G} \end{bmatrix} \quad (3)$$

All simulations performed were generated under a multivariate normal distribution with the covariance structure defined in (3). For a given “subject” i , the latent values are first randomly generated from $MVN(\mathbf{0}, \Sigma)$. Denote the generated latent values for subject i as $\mathbf{L}_i = (y_i, x_i, g_i, s_i, h_i, x'_i, g'_i, e_{X_i}, e_{G_i})^T$. The features for subject i are then completed by generating each sub-matrix through a normal distribution with a mean of the latent value and the corresponding standard deviation. Thus, the i^{th} row of sub-matrix \mathbf{X} is generated by randomly sampling p' values from $N(\mathbf{L}_i[2], Var(X))$, where p' is the number of features contained in sub-matrix \mathbf{X} . A similar process is repeated for the other sub-matrices to complete all components within \mathcal{G} and \mathcal{X} for each subject. After the simulation is complete for \mathbf{Y} , \mathcal{G} , and \mathcal{X} , the values are then centered as a final step. The signal strength may be controlled by calibrating the covariance structure to contain higher correlations amongst the signal latent variables within \mathcal{X} and \mathcal{G} .

Algorithm 1 describes the full details for the steps to execute the simulations performed in this manuscript. Additionally, the simulations may be performed through the `simPathwaySystem` function from the `SuMOFil` R package available at <https://github.com/lorinmil/SuMOFil>. The `simPathwaySystem` function involves many parameters to specify the strength of the network (α , Rsq , $rind$, $noiseSD$), number of features within the datasets (nx , $nxPrime$, ns , ng , $ngPrime$, nh , $ntranscriptNoise$, $ngeneNoise$), and sample size ($nsample$).

This manuscript performed simulations under 9 different simulation settings accounting for all possible

Algorithm 1 Network Simulation

Require: $alpha, Rsq, rind, noiseSD, nx, nxPrime, ns, ng, ngPrime, nh, ntranscriptNoise, ngeneNoise, nsample$

$$\tau = 1$$

$$\beta_{Y|X.G}^2 = \beta_{X|G}^2 = \beta_{Y|S} = \beta_{Y|H} = alpha$$

$$tau = (1 - Rsq)/Rsq$$

$$\sigma_{Y|X.G.S.H} = tau + (alpha * tau)^2 + 2 * tau * alpha^2$$

$$\sigma_{X|G} = alpha * tau$$

$$\sigma_G = 1$$

$$\sigma_S = \sigma_{X|G} + \sigma_G * alpha$$

$$\sigma_H = \sigma_G$$

$$\sigma_{e_X} = \sigma_{e_G} = noiseSD^2$$

Construct $\Sigma_{9 \times 9}$ using formulas from (2) and (3)

$$tauInd = (1 - rind^2)/rind^2$$

for $i = 1$ to $nsample$ **do**

$$\mathbf{L} \sim \mathbf{N}_9(\mathbf{0}, \Sigma)$$

$$\mathbf{Y}[i] \sim N(\mathbf{L}[1], tauInd * \Sigma[1, 1])$$

for $j = 1$ to nx **do**

$$\mathcal{X}[i, j] \sim N(\mathbf{L}[2], tauInd * \Sigma[2, 2])$$

end for

for $j = nx + 1$ to $nx + ns$ **do**

$$\mathcal{X}[i, j] \sim N(\mathbf{L}[4], tauInd * \Sigma[4, 4])$$

end for

for $j = nx + ns + 1$ to $nx + ns + nxPrime$ **do**

$$\mathcal{X}[i, j] \sim N(\mathbf{L}[6], tauInd * \Sigma[6, 6])$$

end for

for $j = nx + ns + nxPrime + 1$ to $nx + ns + nxPrime + ntranscriptNoise$ **do**

$$\mathcal{X}[i, j] \sim N(0, tauInd * \Sigma[8, 8] * \Sigma[1, 1])$$

end for

for $j = 1$ to ng **do**

$$\mathcal{G}[i, j] \sim N(\mathbf{L}[3], tauInd * \Sigma[3, 3])$$

end for

for $j = ng + 1$ to $ng + nh$ **do**

$$\mathcal{G}[i, j] \sim N(\mathbf{L}[5], tauInd * \Sigma[5, 5])$$

end for

for $j = ng + nh + 1$ to $ng + nh + ngPrime$ **do**

$$\mathcal{G}[i, j] \sim N(\mathbf{L}[7], tauInd * \Sigma[7, 7])$$

end for

for $j = ng + nh + ngPrime + 1$ to $ng + nh + ngPrime + ngeneNoise$ **do**

$$\mathcal{G}[i, j] \sim N(0, tauInd * \Sigma[9, 9] * \Sigma[1, 1])$$

end for

end for

$$\mathbf{Y} = \mathbf{Y} - \text{mean}(\mathbf{Y})$$

$$\mathcal{X} = \mathcal{X} - \text{mean}(\mathcal{X})$$

$$\mathcal{G} = \mathcal{G} - \text{mean}(\mathcal{G})$$

return $\mathbf{Y}, \mathcal{X}, \mathcal{G}$

combinations of weak, moderate, and strong network signal strength and small, medium, and large sized datasets. The parameters used in this manuscript are summarized in Table A.

Table A: Simulation Parameter Settings.

Signal Strength			
Parameter	Weak	Moderate	Strong
<i>alpha</i>	0.35	0.35	0.35
<i>Rsq</i>	0.35	0.85	0.85
<i>rind</i>	0.35	0.35	0.85
<i>noiseSD</i>	0.5	1	2
Number of Features			
Parameter	Small	Medium	Large
<i>nx</i>	15	15	15
<i>ns</i>	50	50	50
<i>nxPrime</i>	100	100	100
<i>ntranscriptNoise</i>	5000	15000	25000
<i>ng</i>	10	10	10
<i>nh</i>	30	30	30
<i>ngPrime</i>	100	100	100
<i>ngeneNoise</i>	5000	10000	20000