## **Supplementary Information for:**

- Precision dynamical mapping using topological data analysis 1
- reveals a hub-like transition state at rest 2
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## 18 **Supplementary Figures** 19



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Fig. S1: Step-by-step representation of the Mapper pipeline. First, the high-dimensional 22 neuroimaging data are embedded into a lower dimension set  $d_i$ , using a non-linear filter function 23 f. Here, a nonlinear filter function f based on neighborhood embedding was used (see Methods 24 for benefits of this non-linear approach). Second, overlapping d-dimensional binning is 25 performed to allow for compression and to reduce the destructive effects of noise. Third, partial 26 clustering within each bin is performed, where the original high dimensional information is used 27 for coalescing (or separating) data points into nodes in the low-dimensional space and hence 28 allows for recovering information loss incurred due to dimensional reduction. As a fourth step, to 29 generate a graphical representation of the data landscape, nodes from different bins are 30 connected if any data points are shared between them.

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33 34 35 36 37 38 Fig. S2: Shows hubs across all ten MSC participants. Show Mapper-generated graphs for all 10 MSC participants and their respective data splits. Hubs (i.e., nodes with high degree (>20) and high centrality (top 1%)) are highlighted in blue color. As evident, these hubs were found across all participants and sessions.

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41 42 43 **Fig. S3: RSN-based annotation across all ten MSC participants.** Shows Mapper-generated graphs for all 10 MSC participants. Here, each node is annotated by activation in the known 44 45 large-scale resting state networks. Each node is annotated using a pie-chart to show the proportion of RSNs activated within each node. As evident, topologically highly connected, and 46 centrally located hubs contained brain volumes where no characteristic RSN was activated above the mean, whereas nodes with brain volumes dominating from one (or more) RSN(s) 47 48 tend to occupy the peripheral corners of the landscape. The maps for all individual subjects

- 50 demonstrated this same basic pattern, although there was evidence to suggest that different combinations of RSNs were dominant in different individuals.



51 52 53 54 55 Fig. S4: Gradient was observed across all ten MSC participants. To quantify the variation in RSN-based dominance, we first estimated mean activation for each RSN across the time frames within each node, followed by estimating variation in mean activation across RSNs. High variance (or S.D.) indicated dominance of one or more RSN while low variance (or S.D.) 56 indicated uniformity across RSN activation. Annotating Mapper-generated graphs using 57 variance-based approach revealed a dynamical topographic gradient, where the peripheral

- 58 nodes had higher variance with a continual decrease in variance when going towards the center
- 59 of the graph. This topographic gradient was observed across all participants and sessions.
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65 **temporal masking**. Please note that the frame censoring could only be applied to the data

66 generated from the AR null, as it is a generative model, and we could create same number of

67 TRs as the original (non-censored) data and then drop frames from it to match the number of

frames in the real data. As evident, adding frame censoring to the data generated using AR null

69 did not result in enhancing the number of high degree nodes. Statistically, the proportion of high

degree nodes in real data were still significantly higher than both AR nulls (one-way ANOVA;
 F=4.11, p=0.0276). Only showing data from the odd split, similar results were observed for the

reven split of the data. The shaded area represents standard error around the mean (S.E.M.).



Fig. S6: Parameter perturbation analysis revealed stable results across a moderate range 76 of Mapper parameters. Parameter perturbation analysis was performed to make sure 77 topological properties of the graph (e.g., existence of fat tail in degree distribution) were stable 78 across a moderate range of Mapper parameters. Two main Mapper parameters, i.e., number of 79 bins (a.k.a. Resolution (R)) and percentage overlap between bins (a.k.a. Gain (g)) were varied 80 across the chosen value in the main text (R=30, G=70). The values of R and G were chosen 81 based on our previous work with task fMRI data (Saggar et al. 2018; Nat. Comm.). The heatmap 82 above shows p-values from one-way ANOVAs that examined the proportion of high-degree 83 nodes (>20) in the real versus null data for the odd sessions. As evident, for a large portion of 84 Mapper parameter values, the proportion of high-degree nodes in the real data were 85 significantly higher than null data. We also depict zoomed-in view of degree distribution plots for several parameter combinations (highlighted in red-dashed border on the heatmap) to show the 86 87 excessive proportion of high-degree nodes in real data across different combinations of 88 parameters. The shaded area in the degree distribution plots represents standard error around 89 the mean (S.E.M.). 90

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93 Fig. S7: The nodal mean of each dominant network was propagated into time domain

- 94 (individual TRs) to examine the continuous and transitory nature of RSN-dominance vs
- 95 hub-states. [A] Mapper nodes are annotated by activation in three dominant RSNs relative to
- 96 mean activations of all other RSNs for one representative participant (MSC-01, odd sessions).
  97 As expected, for each dominant RSN, we observed a gradient of mean activation across node.
- As expected, for each dominant RSN, we observed a gradient of mean activation across nodes
  in the Mapper graph such that peripheral nodes contained timeframes (or TRs) with the
- 98 In the Mapper graph such that perpheral hodes contained timenanes (of TRS) with the 99 highest activation, while more central nodes contained TRs with low activation. As evident in
- 100 **[B],** the activation of each of the three dominating networks (default mode, frontoparietal, and
- 101 cingulo-opercular) are continuous in nature and, importantly, the hub-states tend to appear at
- 102 the tails of RSN dominance putatively triggering transitions between RSNs. **[C]** Cortical
- activations are shown for three representative TRs for each dominant network. **[D]** Histogram of
- 104 temporal correlation between the mean amplitude of dominant RSNs and hub-state occurrences
- 105 across all ten participants (separately shown for odd and even sessions). As evident, negative
- 106 relation between the occurrence of hub-states and activation in one or more RSNs was
- 107 observed. The brain overlays were created by the authors using Connectome Workbench Software (https://www.humanconnectome.org/software/connectome-workbench).



109 Fig. S8: Examining connectivity profile of hub states. [A] Functional connectivity derived

110 from timeframes of hub Mapper nodes for one representative participant (MSC01, odd

111 sessions). The connectivity matrix is organized by RSNs. Uniform within network connectivity is

112 observed across all networks. [B] Spider charts showing within-network connectivity (derived

from hubs) across all 10 participants, separately for odd and even sessions. Although Mapper 113

114 graphs were generated using activation data (and not connectivity estimates), within network

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115 functional connectivity derived from hubs also suggest no preference for any RSN.