## **Supplementary Information for:**

- <sup>1</sup> Precision dynamical mapping using topological data analysis
- <sup>2</sup> reveals a hub-like *transition state* at rest
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## 18 **Supplementary Figures** 19



 $^{20}_{21}$ 21 **Fig. S1: Step-by-step representation of the Mapper pipeline.** First, the high-dimensional neuroimaging data are embedded into a lower dimension set  $d_i$ , using a non-linear filter function<br>23 f. Here, a nonlinear filter function f based on neighborhood embedding was used (see Methods 23  $f$ . Here, a nonlinear filter function  $f$  based on neighborhood embedding was used (see Methods 24 for benefits of this non-linear approach). Second, overlapping d-dimensional binning is 24 for benefits of this non-linear approach). Second, overlapping  $d$ -dimensional binning is<br>25 performed to allow for compression and to reduce the destructive effects of noise. Thire performed to allow for compression and to reduce the destructive effects of noise. Third, partial 26 clustering within each bin is performed, where the original high dimensional information is used<br>27 for coalescing (or separating) data points into nodes in the low-dimensional space and hence 27 for coalescing (or separating) data points into nodes in the low-dimensional space and hence<br>28 allows for recovering information loss incurred due to dimensional reduction. As a fourth step, 28 allows for recovering information loss incurred due to dimensional reduction. As a fourth step, to<br>29 generate a graphical representation of the data landscape, nodes from different bins are 29 generate a graphical representation of the data landscape, nodes from different bins are<br>30 connected if any data points are shared between them. connected if any data points are shared between them.

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34 **Fig. S2: Shows hubs across all ten MSC participants.** Show Mapper-generated graphs for all 35 10 MSC participants and their respective data splits. Hubs (i.e., nodes with high degree (>20) 36 and high centrality (top 1%)) are highlighted in blue color. As evident, these hubs were found 37 across all participants and sessions.

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 $^{41}_{42}$ <br> $^{42}_{43}$ 42 **Fig. S3: RSN-based annotation across all ten MSC participants.** Shows Mapper-generated 43 graphs for all 10 MSC participants. Here, each node is annotated by activation in the known<br>44 large-scale resting state networks. Each node is annotated using a pie-chart to show the<br>45 proportion of RSNs activated wit large-scale resting state networks. Each node is annotated using a pie-chart to show the 45 proportion of RSNs activated within each node. As evident, topologically highly connected, and<br>46 centrally located hubs contained brain volumes where no characteristic RSN was activated<br>47 above the mean, whereas nodes centrally located hubs contained brain volumes where no characteristic RSN was activated 47 above the mean, whereas nodes with brain volumes dominating from one (or more) RSN(s)<br>48 tend to occupy the peripheral corners of the landscape. The maps for all individual subjects

- demonstrated this same basic pattern, although there was evidence to suggest that different
- combinations of RSNs were dominant in different individuals.



 $\frac{51}{52}$ Fig. S4: Gradient was observed across all ten MSC participants. To quantify the variation in<br>RSN-based dominance, we first estimated mean activation for each RSN across the time<br>frames within each node, followed by estimat RSN-based dominance, we first estimated mean activation for each RSN across the time frames within each node, followed by estimating variation in mean activation across RSNs. High 55 variance (or S.D.) indicated dominance of one or more RSN while low variance (or S.D.)<br>56 indicated uniformity across RSN activation. Annotating Mapper-generated graphs using 56 indicated uniformity across RSN activation. Annotating Mapper-generated graphs using<br>57 variance-based approach revealed a dynamical topographic gradient, where the periphe variance-based approach revealed a dynamical topographic gradient, where the peripheral

- 58 nodes had higher variance with a continual decrease in variance when going towards the center<br>59 of the graph. This topographic gradient was observed across all participants and sessions.
- of the graph. This topographic gradient was observed across all participants and sessions.
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**temporal masking**. Please note that the frame censoring could only be applied to the data

generated from the AR null, as it is a generative model, and we could create same number of

TRs as the original (non-censored) data and then drop frames from it to match the number of

frames in the real data. As evident, adding frame censoring to the data generated using AR null

69 did not result in enhancing the number of high degree nodes. Statistically, the proportion of high<br>60 degree nodes in real data were still significantly higher than both AR nulls (one-way ANOVA;

degree nodes in real data were still significantly higher than both AR nulls (one-way ANOVA; F=4.11, p=0.0276). Only showing data from the odd split, similar results were observed for the

even split of the data. The shaded area represents standard error around the mean (S.E.M.).





74 75 **Fig. S6: Parameter perturbation analysis revealed stable results across a moderate range**  76 **of Mapper parameters.** Parameter perturbation analysis was performed to make sure<br>77 topological properties of the graph (e.g., existence of fat tail in degree distribution) were 77 topological properties of the graph (e.g., existence of fat tail in degree distribution) were stable<br>78 across a moderate range of Mapper parameters. Two main Mapper parameters, i.e., number o 78 across a moderate range of Mapper parameters. Two main Mapper parameters, i.e., number of 79 bins (a.k.a. Resolution (R)) and percentage overlap between bins (a.k.a. Gain (q)) were varied 79 bins (a.k.a. Resolution (R)) and percentage overlap between bins (a.k.a. Gain (g)) were varied<br>80 across the chosen value in the main text (R=30, G=70). The values of R and G were chosen across the chosen value in the main text ( $R=30$ ,  $G=70$ ). The values of R and G were chosen 81 based on our previous work with task fMRI data (Saggar et al. 2018; Nat. Comm.). The heatmap 82 above shows p-values from one-way ANOVAs that examined the proportion of high-degree<br>83 nodes (>20) in the real versus null data for the odd sessions. As evident, for a large portion 83 nodes (>20) in the real versus null data for the odd sessions. As evident, for a large portion of 84 Mapper parameter values, the proportion of high-degree nodes in the real data were Mapper parameter values, the proportion of high-degree nodes in the real data were 85 significantly higher than null data. We also depict zoomed-in view of degree distribution plots for 86 several parameter combinations (highlighted in red-dashed border on the heatmap) to show the<br>87 excessive proportion of high-degree nodes in real data across different combinations of excessive proportion of high-degree nodes in real data across different combinations of 88 parameters. The shaded area in the degree distribution plots represents standard error around 89 the mean (S.E.M.). 90



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**Fig. S7**: **The nodal mean of each dominant network was propagated into time domain** 

- **(individual TRs) to examine the continuous and transitory nature of RSN-dominance vs**
- **hub-states. [A]** Mapper nodes are annotated by activation in three dominant RSNs relative to
- 96 mean activations of all other RSNs for one representative participant (MSC-01, odd sessions).<br>97 As expected, for each dominant RSN, we observed a gradient of mean activation across nodes
- 97 As expected, for each dominant RSN, we observed a gradient of mean activation across nodes<br>98 in the Mapper graph such that peripheral nodes contained timeframes (or TRs) with the in the Mapper graph – such that peripheral nodes contained timeframes (or TRs) with the
- 
- 99 highest activation, while more central nodes contained TRs with low activation. As evident in 100 **IBI** the activation of each of the three dominating networks (default mode, frontoparietal, and [B], the activation of each of the three dominating networks (default mode, frontoparietal, and
- cingulo-opercular) are continuous in nature and, importantly, the hub-states tend to appear at
- the tails of RSN dominance putatively triggering transitions between RSNs. **[C]** Cortical
- activations are shown for three representative TRs for each dominant network. **[D]** Histogram of
- temporal correlation between the mean amplitude of dominant RSNs and hub-state occurrences
- across all ten participants (separately shown for odd and even sessions). As evident, negative
- 106 relation between the occurrence of hub-states and activation in one or more RSNs was<br>107 observed. The brain overlays were created by the authors using Connectome Workber
- observed. The brain overlays were created by the authors using Connectome Workbench Software (https://www.humanconnectome.org/software/connectome-workbench).



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109 **Fig. S8: Examining connectivity profile of hub states.** [A] Functional connectivity derived 110 from timeframes of hub Mapper nodes for one representative participant (MSC01, odd

from timeframes of hub Mapper nodes for one representative participant (MSC01, odd

111 sessions). The connectivity matrix is organized by RSNs. Uniform within network connectivity is<br>112 observed across all networks. [B] Spider charts showing within-network connectivity (derived

112 observed across all networks. [B] Spider charts showing within-network connectivity (derived<br>113 from hubs) across all 10 participants, separately for odd and even sessions. Although Mapper

from hubs) across all 10 participants, separately for odd and even sessions. Although Mapper

114 graphs were generated using activation data (and not connectivity estimates), within network<br>115 functional connectivity derived from hubs also suggest no preference for any RSN. functional connectivity derived from hubs also suggest no preference for any RSN.