Mapping global dynamics of benchmark creation and saturation in artificial intelligence

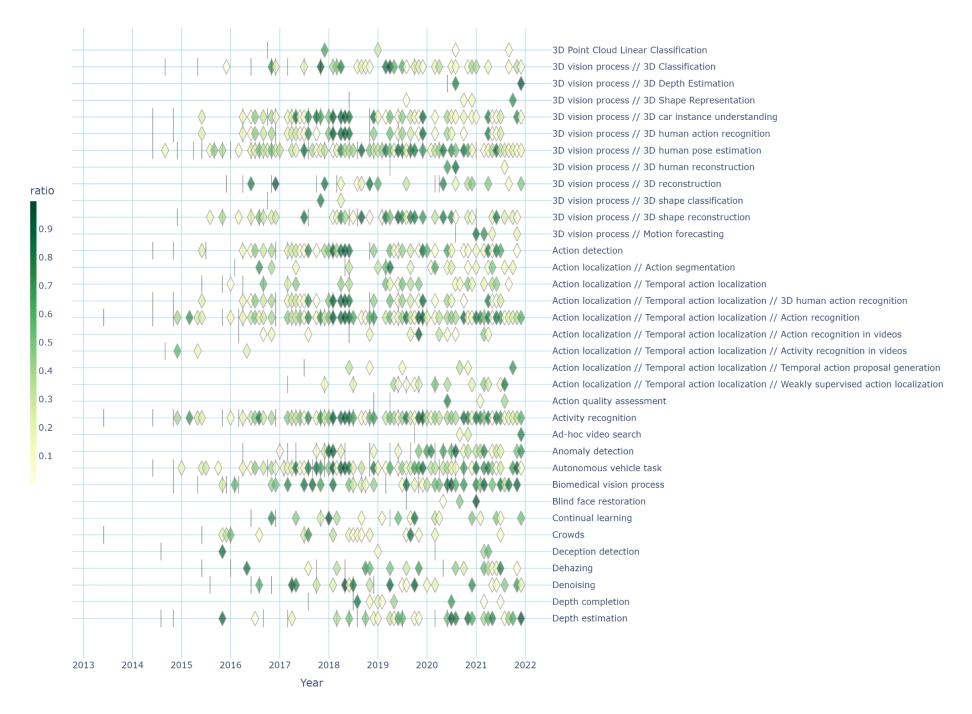
Supplementary Information

Supplementary Figure 1: Global SOTA improvement map for computer vision. Anchors (vertical dashes) and only multiple dot trajectories shown in the plot.

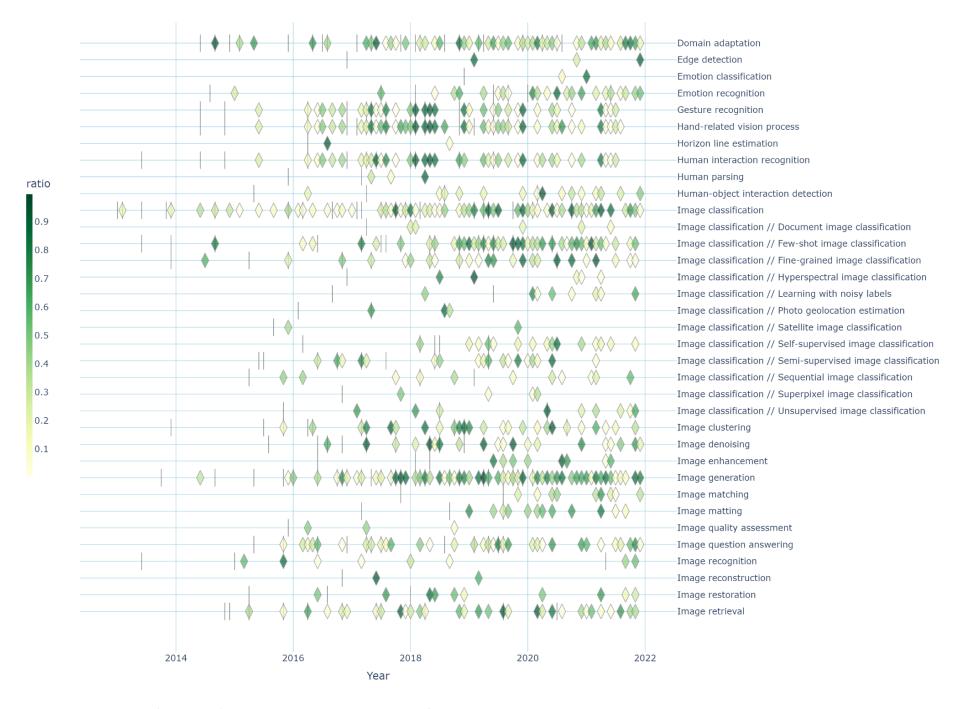
Supplementary Figure 2: AI benchmark lifecycle map for computer vision.

Supplementary Figure 3: Number of active benchmarks vs. number of benchmarks reporting novel SOTA results over time for computer vision tasks.

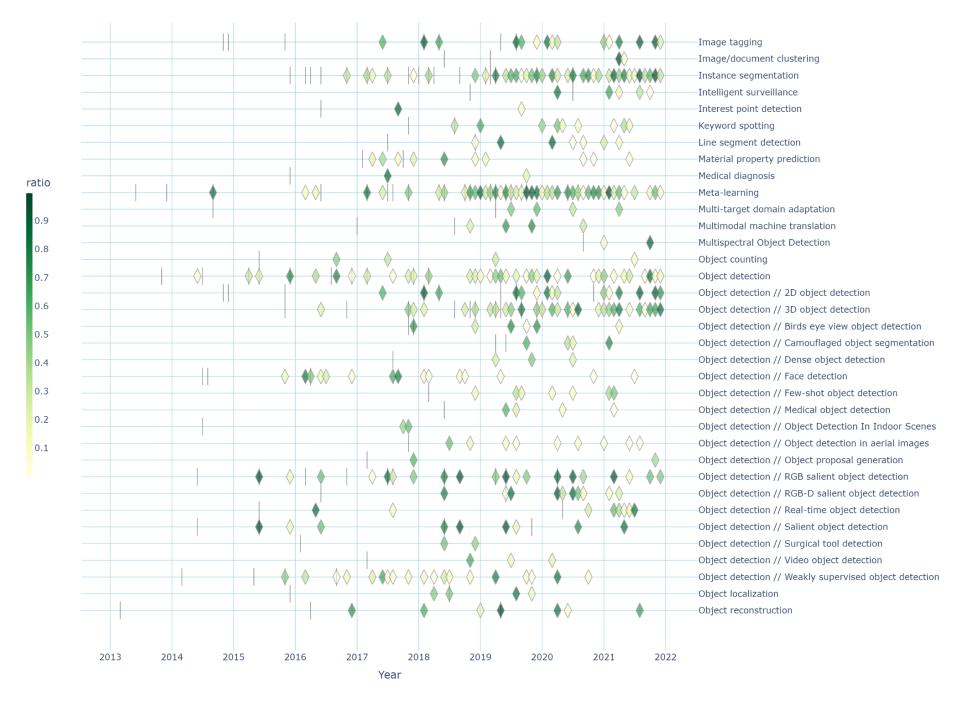
High definition images of all figures are available here: https://drive.google.com/drive/folders/12aA8t49sp7hxqVZJdWCrh-gvVolxtYeh



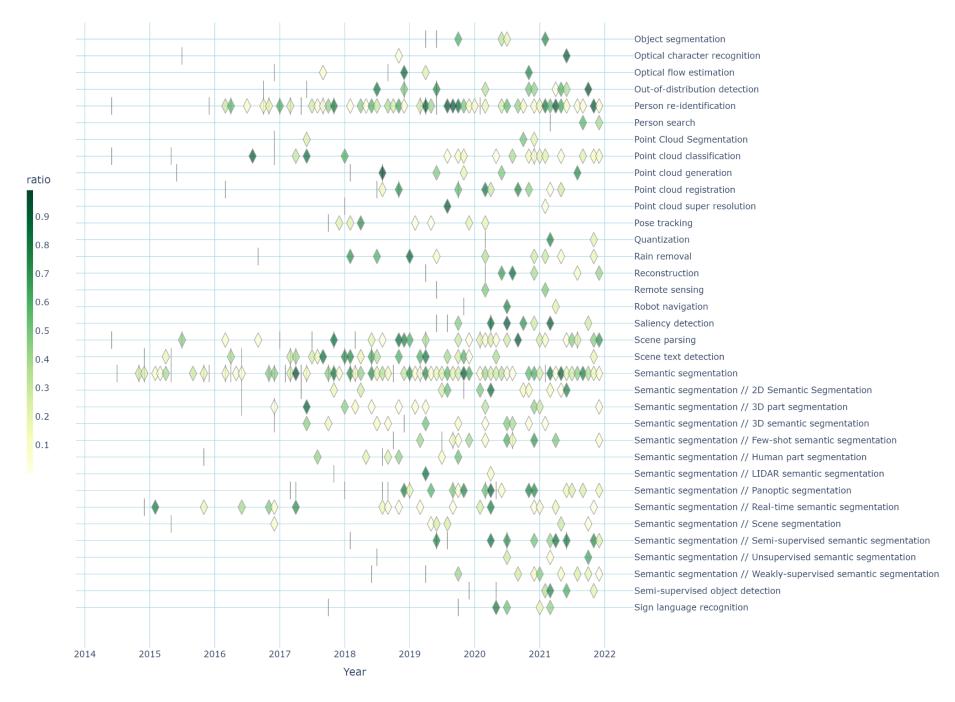
Supplementary Figure 1 (continued on following pages): Global SOTA improvement map for computer vision.



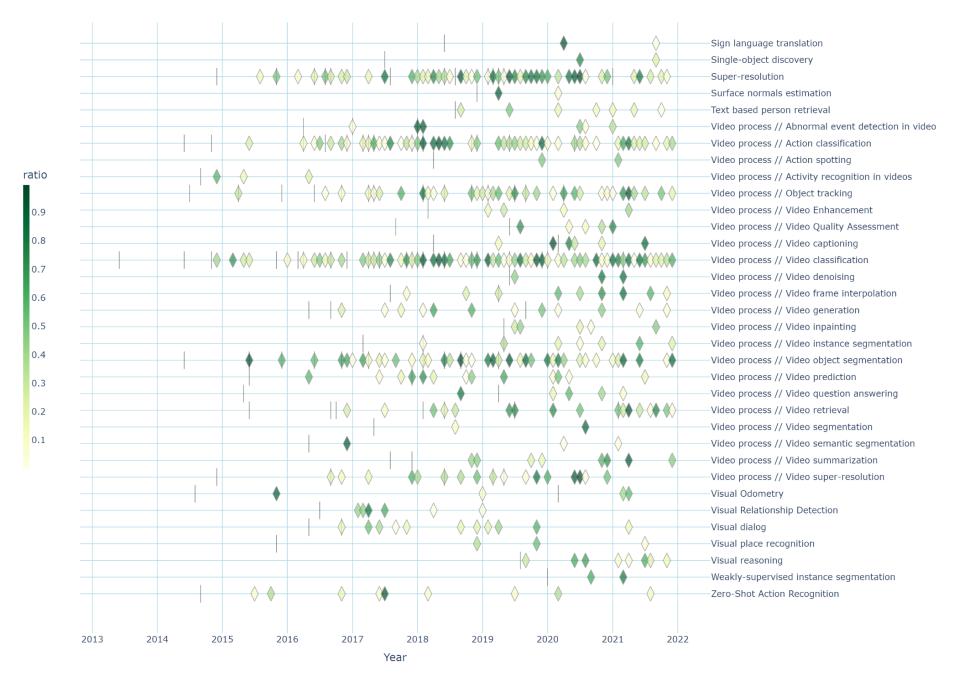
Supplementary Figure 1 (continued): Global SOTA improvement map for computer vision.



Supplementary Figure 1 (continued): Global SOTA improvement map for computer vision.



Supplementary Figure 1 (continued): Global SOTA improvement map for computer vision.



Supplementary Figure 1 (continued): Global SOTA improvement map for computer vision.



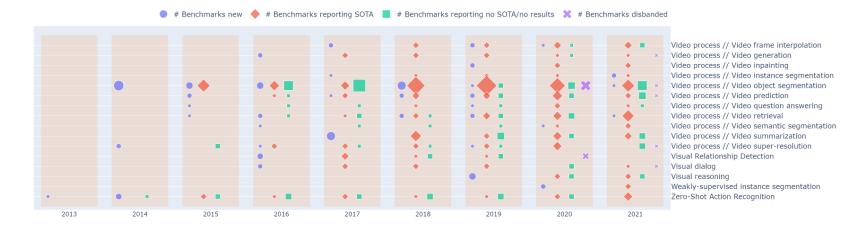
Supplementary Figure 2 (continued on following pages): AI benchmark lifecycle map for computer vision.



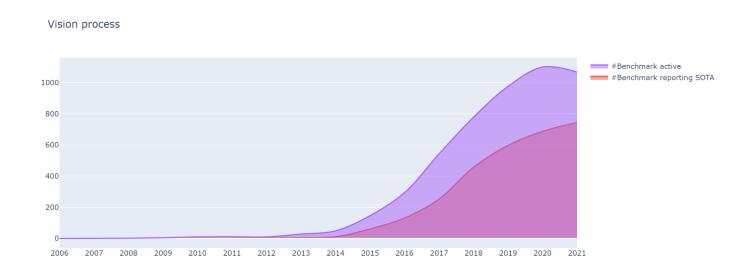
Supplementary Figure 2 (continued): AI benchmark lifecycle map for computer vision.



Supplementary Figure 2 (continued): AI benchmark lifecycle map for computer vision.



Supplementary Figure 2 (continued): AI benchmark lifecycle map for computer vision.



Supplementary Figure 3: Number of active benchmarks vs. number of benchmarks reporting novel SOTA results over time for computer vision tasks.