

**Supporting Information.** Gardner, B., B. T. McClintock, S. J. Converse, and N. J. Hostetter. 2022. Integrated animal movement and spatial capture-recapture models: Simulation, implementation, and inference. *Ecology*.

## Appendix S1

This appendix includes the summaries of all the parameters in each of the 18 Scenarios presented in the main text, including Scenarios 1–6 with  $T = 15$  and Scenarios 7A–12A which include telemetered individuals. These results are presented in Tables [S1](#) - [S5](#).

Table [S6](#) includes the average number of captures and recaptures for each scenario along with the number of simulations that did not converge according the R-hat values. We note that many of these simulations would have resulted in convergence if we had set the number of iterations higher in the MCMC settings, but this would have made the simulation study prohibitively long. For Scenarios 7-12, we ran 100,000 iterations, and in most cases  $\gamma$  was the parameter that did not converge due to mostly to slow mixing. In comparing the number of captured and recaptured individuals, as well as the parameter estimates and standard deviations between simulated datasets where the models converged and those that didn't, we found little to no difference.

<b>Parameter</b>	<b>True</b>	<b>Mean</b>	<b>sd</b>	<b>median</b>	<b>2.5%</b>	<b>97.5%</b>	<b>Coverage</b>
<b>Scenario 1</b>							
N	100.00	102.243	20.443	100.590	69.930	146.850	98
$\sigma$	0.10	0.100	0.009	0.100	0.084	0.121	93
$\sigma_{det}$	0.05	0.051	0.005	0.051	0.042	0.060	96
$\lambda_0$	3.00	3.090	0.565	3.036	2.145	4.352	95
<b>Scenario 2</b>							
N	100.00	100.437	17.617	99.210	69.490	138.260	96
$\sigma$	0.10	0.100	0.007	0.100	0.087	0.114	94
$\sigma_{det}$	0.10	0.100	0.004	0.100	0.092	0.109	97
$\lambda_0$	2.00	2.042	0.231	2.028	1.630	2.535	94
<b>Scenario 3</b>							
N	100.00	100.855	17.4124	99.660	70.220	138.19	94
$\sigma$	0.10	0.103	0.010	0.102	0.084	0.123	95
$\sigma_{det}$	0.15	0.149	0.010	0.149	0.131	0.169	99
$\lambda_0$	0.50	0.520	0.081	0.514	0.380	0.698	97
<b>Scenario 4</b>							
N	100.00	100.083	18.430	98.640	68.110	140.090	97
$\sigma$	0.20	0.203	0.018	0.202	0.171	0.241	91
$\sigma_{det}$	0.05	0.050	0.004	0.050	0.042	0.059	95
$\lambda_0$	3.00	3.157	0.577	3.103	2.188	4.441	91
<b>Scenario 5</b>							
N	100.00	101.407	15.556	100.470	73.770	134.570	95
$\sigma$	0.20	0.201	0.010	0.201	0.182	0.222	92
$\sigma_{det}$	0.10	0.099	0.004	0.099	0.091	0.108	95
$\lambda_0$	2.00	2.052	0.227	2.039	1.642	2.532	97
<b>Scenario 6</b>							
N	100.00	98.619	15.614	97.570	71.020	131.940	96
$\sigma$	0.20	0.200	0.014	0.200	0.173	0.230	94
$\sigma_{det}$	0.15	0.152	0.012	0.151	0.130	0.177	95
$\lambda_0$	0.50	0.507	0.090	0.500	0.350	0.704	99

Table S1: Summaries of the parameter estimates for each of the simulation scenarios of the simple random walk model (labeled as Scenarios 1 – 6 in the main text). Each scenario has  $T = 25$  sampling occasions.

<b>Parameter</b>	<b>True</b>	<b>Mean</b>	<b>sd</b>	<b>median</b>	<b>2.5%</b>	<b>97.5%</b>	<b>Coverage</b>
<b>Scenario 1 T = 15</b>							
N	100.00	104.916	26.021	101.860	62.720	164.280	97
$\sigma$	0.10	0.102	0.014	0.101	0.078	0.133	96
$\sigma_{det}$	0.05	0.050	0.007	0.050	0.038	0.064	98
$\lambda_0$	3.00	3.246	0.799	3.141	1.992	5.106	90
<b>Scenario 2 T = 15</b>							
N	100.00	100.719	18.528	99.390	68.320	140.680	96
$\sigma$	0.10	0.100	0.010	0.099	0.082	0.120	95
$\sigma_{det}$	0.10	0.101	0.006	0.100	0.090	0.112	100
$\lambda_0$	2.00	2.038	0.302	2.014	1.517	2.696	94
<b>Scenario 3 T = 15</b>							
N	100.00	102.192	18.544	100.880	69.720	142.090	93
$\sigma$	0.10	0.102	0.015	0.102	0.075	0.133	93
$\sigma_{det}$	0.15	0.148	0.013	0.148	0.125	0.175	96
$\lambda_0$	0.50	0.538	0.110	0.527	0.354	0.783	95
<b>Scenario 4 T = 15</b>							
N	100.00	101.301	22.751	98.980	63.580	152.480	95
$\sigma$	0.20	0.204	0.026	0.202	0.160	0.262	96
$\sigma_{det}$	0.05	0.052	0.006	0.051	0.040	0.064	99
$\lambda_0$	3.00	3.187	0.771	3.091	1.9624	4.969	93
<b>Scenario 5 T = 15</b>							
N	100.00	101.814	17.016	100.650	71.750	138.300	95
$\sigma$	0.20	0.200	0.014	0.199	0.174	0.228	93
$\sigma_{det}$	0.10	0.100	0.006	0.100	0.090	0.111	92
$\lambda_0$	2.00	2.037	0.292	2.016	1.524	2.665	92
<b>Scenario 6 T = 15</b>							
N	100.00	97.450	17.102	96.270	67.530	134.300	93
$\sigma$	0.20	0.199	0.021	0.198	0.160	0.243	95
$\sigma_{det}$	0.15	0.154	0.016	0.153	0.126	0.189	96
$\lambda_0$	0.50	0.508	0.118	0.496	0.312	0.771	93

Table S2: Summaries of the parameter estimates for each of the simulation scenarios of the simple random walk model (labeled as Scenarios 1 – 6 in the main text). Each scenario has  $T = 15$  sampling occasions in this set of simulations.

<b>Parameter</b>	<b>True</b>	<b>Mean</b>	<b>sd</b>	<b>median</b>	<b>2.5%</b>	<b>97.5%</b>	<b>Coverage</b>
<b>Scenario 7</b>							
N	100.00	101.376	18.114	100.060	69.820	140.480	95
$\sigma$	0.10	0.110	0.016	0.109	0.082	0.142	92
$\sigma_{det}$	0.05	0.050	0.003	0.050	0.043	0.057	99
$\lambda_0$	5.00	5.120	0.738	5.056	3.862	6.752	98
$\gamma$	0.50	0.411	0.118	0.416	0.168	0.624	97
<b>Scenario 8</b>							
N	100.00	99.419	15.740	98.400	71.550	133.070	96
$\sigma$	0.10	0.101	0.010	0.100	0.083	0.121	95
$\sigma_{det}$	0.10	0.100	0.003	0.100	0.094	0.107	99
$\lambda_0$	3.00	3.032	0.272	3.018	2.538	3.604	95
$\gamma$	0.50	0.489	0.074	0.492	0.335	0.624	96
<b>Scenario 9</b>							
N	100.00	99.561	15.331	98.540	72.350	132.310	97
$\sigma$	0.10	0.107	0.016	0.106	0.079	0.140	97
$\sigma_{det}$	0.15	0.149	0.006	0.149	0.138	0.162	93
$\lambda_0$	1.00	1.024	0.105	1.019	0.835	1.245	90
$\gamma$	0.50	0.458	0.105	0.464	0.233	0.643	97
<b>Scenario 10</b>							
N	100.00	101.556	16.328	100.410	73.040	136.820	96
$\sigma$	0.20	0.219	0.031	0.217	0.166	0.287	93
$\sigma_{det}$	0.05	0.049	0.004	0.049	0.043	0.056	94
$\lambda_0$	5.00	5.251	0.748	5.187	3.972	6.901	94
$\gamma$	0.50	0.416	0.121	0.425	0.161	0.625	93
<b>Scenario 11</b>							
N	100.00	98.839	12.860	98.040	75.820	126.160	97
$\sigma$	0.20	0.203	0.013	0.202	0.178	0.230	97
$\sigma_{det}$	0.10	0.100	0.003	0.100	0.094	0.107	94
$\lambda_0$	3.00	3.030	0.268	3.017	2.542	3.590	94
$\gamma$	0.50	0.489	0.056	0.491	0.373	0.594	95
<b>Scenario 12</b>							
N	100.00	99.434	13.837	98.550	74.820	128.930	97
$\sigma$	0.20	0.214	0.029	0.213	0.163	0.272	89
$\sigma_{det}$	0.15	0.147	0.012	0.146	0.127	0.172	93
$\lambda_0$	0.50	0.542	0.096	0.535	0.375	0.749	96
$\gamma$	0.50	0.443	0.102	0.448	0.229	0.626	91

Table S3: Summaries of the parameter estimates for each of the simulation scenarios of the correlated random walk model (labeled as Scenarios 7 – 12 in the main text).

<b>Parameter</b>	<b>True</b>	<b>Mean</b>	<b>sd</b>	<b>median</b>	<b>2.5%</b>	<b>97.5%</b>	<b>Coverage</b>
<b>Scenario 7A</b>							
N	100.00	100.538	16.740	99.290	71.350	136.640	98
$\sigma$	0.10	0.101	0.004	0.101	0.092	0.109	92
$\sigma_{det}$	0.05	0.050	0.001	0.050	0.047	0.053	93
$\lambda_0$	5.00	5.112	0.649	5.062	3.984	6.527	95
$\gamma$	0.50	0.492	0.043	0.493	0.407	0.574	94
<b>Scenario 8A</b>							
N	100.00	98.905	14.802	97.900	72.85	130.680	96
$\sigma$	0.10	0.100	0.006	0.100	0.089	0.112	96
$\sigma_{det}$	0.10	0.100	0.002	0.100	0.096	0.104	95
$\lambda_0$	3.00	3.035	0.228	3.025	2.616	3.508	96
$\gamma$	0.50	0.499	0.048	0.500	0.400	0.590	98
<b>Scenario 9A</b>							
N	100.00	100.305	14.565	99.360	74.605	131.490	96
$\sigma$	0.10	0.102	0.009	0.101	0.085	0.120	96
$\sigma_{det}$	0.15	0.150	0.004	0.150	0.143	0.157	93
$\lambda_0$	1.00	1.004	0.075	1.002	0.865	1.159	93
$\gamma$	0.50	0.485	0.066	0.487	0.348	0.605	96
<b>Scenario 10A</b>							
N	100.00	100.244	14.490	99.230	74.760	131.370	95
$\sigma$	0.20	0.200	0.007	0.200	0.187	0.214	97
$\sigma_{det}$	0.05	0.050	0.001	0.050	0.047	0.053	93
$\lambda_0$	5.00	5.066	0.644	5.017	3.945	6.465	96
$\gamma$	0.50	0.499	0.038	0.499	0.424	0.573	94
<b>Scenario 11A</b>							
N	100.00	99.159	12.086	98.440	77.620	124.78	98
$\sigma$	0.20	0.201	0.007	0.201	0.187	0.216	96
$\sigma_{det}$	0.10	0.100	0.002	0.100	0.096	0.105	92
$\lambda_0$	3.00	3.007	0.224	2.998	2.594	3.472	95
$\gamma$	0.50	0.497	0.036	0.497	0.424	0.567	99
<b>Scenario 12A</b>							
N	100.00	100.046	12.957	99.190	77.050	127.680	97
$\sigma$	0.20	0.203	0.011	0.202	0.182	0.225	98
$\sigma_{det}$	0.15	0.149	0.004	0.149	0.143	0.158	95
$\lambda_0$	0.50	0.511	0.053	0.508	0.413	0.621	94
$\gamma$	0.50	0.487	0.048	0.488	0.389	0.578	94

Table S4: Summaries of the parameter estimates for each of the simulation scenarios of the correlated random walk model with 10 telemetered individuals where auxiliary location data are included (labeled as Scenarios 7A – 12A in the main text).

<b>Parameter</b>	<b>True</b>	<b>Mean</b>	<b>sd</b>	<b>median</b>	<b>2.5%</b>	<b>97.5%</b>	<b>Coverage</b>
<b>Scenario 13</b>							
N	100.00	104.707	17.262	103.580	74.240	141.740	96
$\sigma$	0.10	0.101	0.007	0.100	0.088	0.114	94
$\sigma_{det}$	0.10	0.100	0.004	0.100	0.092	0.108	97
$\lambda_0$	2.00	2.030	0.217	2.018	1.641	2.491	95
$\delta$	0.70	0.720	0.210	0.720	0.312	1.134	93
<b>Scenario 14</b>							
N	100.00	102.163	17.568	100.860	71.380	139.950	95
$\sigma$	0.10	0.100	0.007	0.100	0.087	0.113	93
$\sigma_{det}$	0.10	0.100	0.004	0.100	0.092	0.108	97
$\lambda_0$	2.00	2.034	0.224	2.021	1.634	2.512	96
$\delta$	0.30	0.304	0.214	0.304	-0.116	0.723	99
<b>Scenario 15</b>							
N	100.00	100.629	15.742	99.590	72.710	134.200	94
$\sigma$	0.20	0.200	0.013	0.199	0.176	0.226	95
$\sigma_{det}$	0.10	0.101	0.008	0.100	0.087	0.117	97
$\lambda_0$	1.00	1.020	0.175	1.007	0.716	1.400	97
$\delta$	0.70	0.702	0.201	0.698	0.316	1.107	94
<b>Scenario 16</b>							
N	100.00	103.737	16.456	102.620	7.660	138.980	97
$\sigma$	0.20	0.199	0.013	0.199	0.176	0.226	96
$\sigma_{det}$	0.10	0.099	0.007	0.099	0.086	0.115	97
$\lambda_0$	1.00	1.046	0.178	1.033	0.737	1.432	95
$\delta$	0.30	0.280	0.189	0.279	-0.089	0.654	90
<b>Scenario 17</b>							
N	100.00	104.989	18.054	103.670	73.460	143.865	93
$\sigma$	0.20	0.201	0.016	0.200	0.172	0.236	94
$\sigma_{det}$	0.05	0.051	0.004	0.051	0.043	0.060	93
$\lambda_0$	3.00	3.035	0.525	2.988	2.144	4.197	94
$\delta$	0.70	0.679	0.228	0.673	0.245	1.140	98
<b>Scenario 18</b>							
N	100.00	104.178	18.509	102.720	72.030	144.335	97
$\sigma$	0.20	0.202	0.017	0.201	0.172	0.237	93
$\sigma_{det}$	0.05	0.050	0.004	0.050	0.043	0.059	95
$\lambda_0$	3.00	3.210	0.565	3.159	2.269	4.439	95
$\delta$	0.30	0.335	0.221	0.332	-0.092	0.776	93

Table S5: Summaries of the parameter estimates for each of the simulation scenarios of the integrated Langevin-SCR model (labeled as Scenarios 13 – 18 in the main text).

<b>Scenario</b>	<b>Model type</b>	$n$	<b>recaps</b>	<b>failed convergence</b>
1	Simple random walk	20.94	5.81	22
2	Simple random walk	24.60	12.78	4
3	Simple random walk	25.23	7.08	16
4	Simple random walk	24.12	4.96	34
5	Simple random walk	30.23	10.49	0
6	Simple random walk	28.83	5.95	5
<b>Scenario</b>	<b>Model type</b>	$n$	<b>recaps</b>	<b>failed convergence</b>
1T15	Simple RW with T=15	17.70	4.16	19
2T15	Simple RW with T=15	22.80	8.27	0
3T15	Simple RW with T=15	23.47	4.62	30
4T15	Simple RW with T=15	19.6	3.62	28
5T15	Simple RW with T=15	26.62	7.22	0
6T15	Simple RW with T=15	24.76	4.12	4
<b>Scenario</b>	<b>Model type</b>	$n$	<b>recaps</b>	<b>failed convergence</b>
7	Correlated random walk	24.65	7.99	57
8	Correlated random walk	28.75	16.42	9
9	Correlated random walk	29.94	11.83	22
10	Correlated random walk	30.64	6.47	92
11	Correlated random walk	38.00	12.27	6
12	Correlated random walk	35.42	5.03	46
<b>Scenario</b>	<b>Model type</b>	$n$	<b>recaps</b>	<b>failed convergence</b>
7A	Correlated RW with telemetry	24.66	7.99	10
8A	Correlated RW with telemetry	28.87	16.37	4
9A	Correlated RW with telemetry	30.32	11.86	13
10A	Correlated RW with telemetry	30.68	6.25	20
11A	Correlated RW with telemetry	38.08	12.27	7
12A	Correlated RW with telemetry	35.78	4.95	8
<b>Scenario</b>	<b>Model type</b>	$n$	<b>recaps</b>	<b>failed convergence</b>
13	Langevin	27.33	12.84	4
14	Langevin	25.86	12.88	5
15	Langevin	29.41	5.74	5
16	Langevin	29.52	5.72	8
17	Langevin	26.89	4.94	39
18	Langevin	26.00	5.06	39

Table S6: For each scenario, we report the average number of individuals captured,  $n$ , the average number of recaptures, 'recaps', and the number of simulated datasets where the model did not converge based on the R-hat, 'failed convergence'. See discussion at the beginning of this appendix for more details on the convergence results.